



IMU381ZA

INERTIAL MEASUREMENT SYSTEM

The IMU381ZA is an improved version of the popular IMU380ZA miniature fully-calibrated Inertial Measurement System. The changes include better gyro performance, improved synchronization capability, and a bootloader function, which allows field upgrade-ability and also enables customers to take advantage of the ACEINNA open source navigation software development platform.



Precision Farming



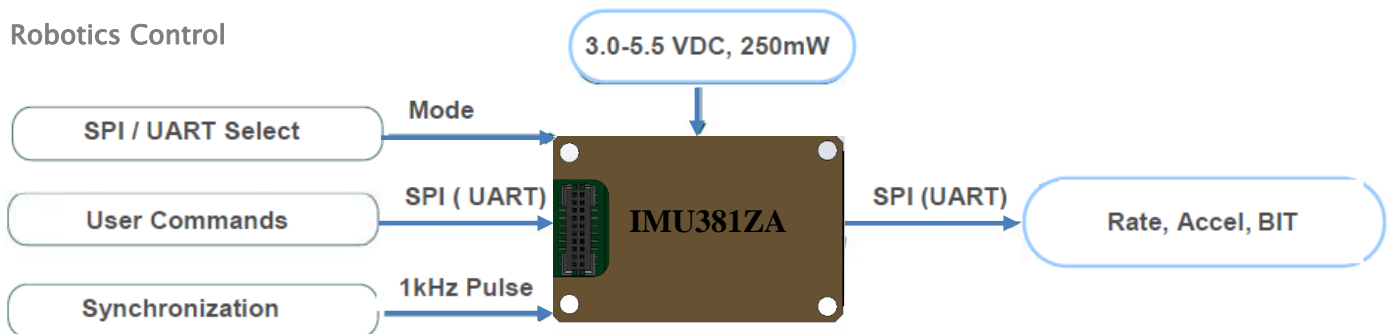
Platform Stabilization

The ACEINNA IMU381ZA integrates highly-reliable MEMS 6DOF inertial sensors in a miniature factory-calibrated module to provide consistent performance through the extreme operating environments in a wide variety of dynamic control and navigation applications.

Applications

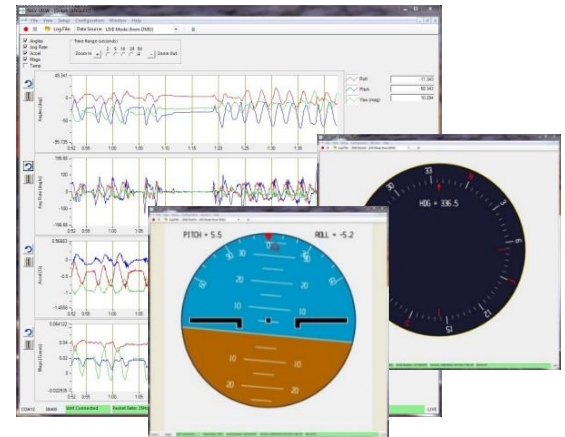
- Unmanned Vehicle Control
- Precision Agriculture
- Platform Stabilization
- Robotics Control

- ### Features
- Complete 6DOF Inertial System
 - SPI (or UART) Interface
 - Update Rate, 1Hz to 200Hz
 - 1KHz Clock Sync Input
 - Miniature Package, 24 x 37 x 9.5 mm
 - Drop-in upgrade for IMU380ZA
 - Low Power Consumption < 250 mW
 - Wide Temp Range, -40C to +85C
 - High Reliability, MTBF > 50k hours



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NAV-VIEW provides an easy to use graphical interface to display, record, playback, and analyze all of the IMU381ZA system parameters.

NAV-VIEW can also be used to set a wide range of user-configurable fields in the IMU381ZA to optimize the system performance for highly dynamic applications.

NAV-VIEW software is available for download from ACEINNA's website at: www.aceinna.com/support

EVAL KIT

The DMU381ZA evaluation kits include an IMU381ZA, evaluation / interface board and USB cable allowing direct connection to a PC for use with NAV-VIEW display and configuration software.



Support

For more detailed information please refer to the DMU381ZA Series User's Manual available online at: www.aceinna.com/support

Performance IMU381ZA (-200/400)

Angular Rate	
Range: Roll, Pitch (°/sec)	± 200 (± 400 High Range Model)
Bias Instability (°/hr) ^{1,2}	6
Bias Stability Over Temp (°/sec) ³	< 0.5
Resolution (°/sec)	< 0.02
Scale Factor Accuracy (%)	< 0.1
Non-Linearity (%FS)	< 0.1
Angle Random Walk (°/√hr) ^{1,2}	0.3
Bandwidth (Hz)	5-50 (user-configurable)
Acceleration	
Range: X, Y, Z (g)	± 4 (± 8 High Range Model)
Bias Instability (mg) ^{1,2}	0.02
Bias Stability Over Temp (mg) ³	< 5
Resolution (mg)	< 0.5
Scale Factor Accuracy ¹ (-40 to 85 C) (%)	0.6
Non-Linearity (%FS)	< 0.1
Velocity Random Walk (m/s/√hr) ^{1,2}	0.05
Bandwidth (Hz)	5-50 (user-configurable)

Other Specifications

Environment	
Operating Temperature (°C)	-40 to +85
Non-Operating Temperature (°C)	-55 to +105
Enclosure	Die-Cast Aluminum
Electrical	
Input Voltage (VDC)	3.0 to 5.5
Power Consumption (mW)	< 250
Digital Interface	SPI or UART (user-configurable)
Output Data Rate	1Hz to 200Hz (user-configurable)
Input Clock Sync	1kHz Sync Pulse
Physical	
Size (mm)	24.15 x 37.7 x 9.5
Weight (gm)	< 17
Interface Connector	20-Pin (10 x 2) 1.0 mm pitch header

Ordering Information

Model	Description
IMU381ZA-200	Inertial Measurement Unit (6 DOF, 200dps Range)
IMU381ZA-400	Inertial Measurement Unit (6 DOF, 400dps Range)
EVAL-KIT DMU381ZA-200	Evaluation Kit for DMU381 Family (Std Range)
EVAL-KIT DMU381ZA-400	Evaluation Kit for DMU381 Family (High Range)

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¹ Allan Variance Curve, constant temperature. ² 1-sigma error. ³ RMS error over temperature